



HITACHI
S10 α SERIES

SOFTWARE MANUAL
OPTION

HIGH SPEED REMOTE I/O

For Windows[®]

2 α
SERIES

Applicable to :

| | |
|---------------------------|--------------------|
| HITACHI-S10/2 α | NESP-S25E |
| HITACHI-S10/2 α E | NESP-2 α E |
| HITACHI-S10/2 α H | NESP-2 α H |
| HITACHI-S10/2 α Hf | NESP-2 α Hf |

NOTE

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SAFETY PRECAUTIONS

- Read this manual thoroughly and follow all the safety precautions and instructions given in this manual before operations such as system configuration and program creation.
- Keep this manual handy so that you can refer to it any time you want.
- If you have any question concerning any part of this manual, contact your nearest Hitachi branch office or service engineer.
- Hitachi will not be responsible for any accident or failure resulting from your operation in any manner not described in this manual.
- Hitachi will not be responsible for any accident or failure resulting from modification of software provided by Hitachi.
- Hitachi will not be responsible for reliability of software not provided by Hitachi.
- Make it a rule to back up every file. Any trouble on the file unit, power failure during file access or incorrect operation may destroy some of the files you have stored. To prevent data destruction and loss, make file backup a routine task.
- Furnish protective circuits externally and make a system design in a way that ensures safety in system operations and provides adequate safeguards to prevent personal injury and death and serious property damage even if the product should become faulty or malfunction or if an employed program is defective.
- If an emergency stop circuit, interlock circuit, or similar circuit is to be formulated, it must be positioned external to the programmable controller. If you do not observe this precaution, equipment damage or accident may occur when the programmable controller becomes defective.
- Before changing the program, generating a forced output, or performing the RUN, STOP, or like procedure during an operation, thoroughly verify the safety because the use of an incorrect procedure may cause equipment damage or other accident.



“RUN/STOP” SWITCH CAUTION

The “RUN/STOP” switch only stops execution of the ladder logic program or HI-FLOW program. Digital and analog outputs are left in the active state when execution stops, unless the optional rungs described in the CPU manual have been added. The “RUN/STOP” switch does not affect the operation of C-language or FA-BASIC language programs. Outputs can still be produced in response to C-language or FA-BASIC programs, or by the action of programmers typing in commands in these languages, while the “RUN/STOP” switch is in the “STOP” position.

DO NOT DEPEND ON THE STOP SWITCH TO STOP MOVING PARTS OR TO PREVENT UNEXPECTED MOTION OR ENERGIZATION. USE HARDWIRED SAFETY DISCONNECT AND LOCK OUT POWER AND CONTROL VOLTAGES BEFORE WORKING ON ELECTRICAL CIRCUITS OR PARTS THAT CAN MOVE.

PREFACE

We greatly appreciate your purchase of this high-speed remote I/O system.

The high-speed remote I/O system runs on a personal computer and carries out a variety of setup operations for high-speed remote I/O modules.

This manual describes the operation of the high-speed remote I/O system.

This manual is applicable to the following system versions.

| System name/version |
|---|
| HIGH SPEED REMOTE I/O SYSTEM For Windows® 07-01 |

System versions 05-00 and earlier do not support the Microsoft® Windows® 98 operating system.

They support the Microsoft® Windows® 95 operating system only.

For high-speed remote I/O modules, refer to the following manual supplied with the module.

<Related manual>

OPTION MANUAL HIGH SPEED REMOTE I/O (Manual number SP-62-105)

See the following list when you use the NESP
(Nissan Electronic Sequence Processor) series.

| 【HITACHI-S10 α series】 | | 【NESP series】 |
|-------------------------------|-------|--------------------|
| HITACHI-S10/2 α | | NESP-S25E |
| HITACHI-S10/2 α E | | NESP-2 α E |
| HITACHI-S10/2 α H | | NESP-2 α H |
| HITACHI-S10/2 α Hf | | NESP-2 α Hf |

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- Ethernet is a registered trademark of Xerox Corp.

Other product names written in this manual are the trademarks of each manufacturer.

Systems Supported by Windows® 2000 and Windows® XP

The systems supported by Microsoft® Windows® 2000 operating system (hereafter abbreviated as Windows® 2000) and Microsoft® Windows® XP operating system (hereafter abbreviated as Windows® XP) are shown in the following table.

Systems of earlier versions than those shown in the following table are not supported by Windows® 2000 and Windows® XP but supported by only Microsoft® Windows® 95 operating system (hereafter abbreviated as Windows® 95) and Microsoft® Windows® 98 operating system (hereafter abbreviated as Windows® 98). (The system names in the following table are hereafter abbreviated as each system.)

<Table of Systems Supported by Windows® 2000 and Windows® XP>

| No. | System name | Type | Version | Windows® 2000 | Windows® XP |
|-----|--|-----------|---------|---------------|-------------|
| 1 | S10Tools SYSTEM | S-7890-01 | 07-05 | √ | √ |
| 2 | LADDER CHART SYSTEM | S-7890-02 | 07-05 | √ | √ |
| 3 | HI-FLOW SYSTEM | S-7890-03 | 07-02 | √ | √ |
| 4 | CPMS LOADING SYSTEM | S-7890-04 | 07-04 | √ | √ |
| 5 | CPMSE LOADING SYSTEM | S-7890-05 | 07-04 | √ | √ |
| 6 | CPMS DEBUGGER SYSTEM | S-7890-06 | 07-02 | √ | √ |
| 7 | CPMSE DEBUGGER SYSTEM | S-7890-07 | 07-02 | √ | √ |
| 8 | GP-IB LOADING SYSTEM | S-7890-08 | 07-01 | √ | √ |
| 9 | BACKUP RESTORE SYSTEM | S-7890-09 | 08-01 | √ | √ |
| 10 | RPDP/S10 SYSTEM | S-7891-10 | 03-03 | √ (*2) | ns (*1) |
| 11 | NX/Tools-S10 SYSTEM | S-7890-13 | 07-02 | √ | √ |
| 12 | 4α LADDER CHART SYSTEM | S-7890-17 | 07-05 | √ | √ |
| 13 | 4αH LADDER CHART SYSTEM | S-7890-18 | 07-05 | √ | √ |
| 14 | LADDER COMMENT CONVERTER SYS | S-7890-19 | 06-01 | √ | √ |
| 15 | HIGH SPEED REMOTE I/O SYSTEM | S-7890-21 | 07-01 | √ | √ |
| 16 | CPU LINK SYSTEM | S-7890-22 | 07-01 | √ | √ |
| 17 | 4ch ANALOG PULSE COUNTER SYS | S-7890-23 | 07-01 | √ | √ |
| 18 | EXTERNAL SERIAL LINK SYSTEM | S-7890-24 | 07-02 | √ | √ |
| 19 | S10ET LINK SYSTEM | S-7890-25 | 07-02 | √ | √ |
| 20 | J.NET SYSTEM | S-7890-27 | 07-02 | √ | √ |
| 21 | OD.RING/SD.LINK SYSTEM | S-7890-28 | 07-03 | √ | √ |
| 22 | ET.NET SYSTEM | S-7890-29 | 07-01 | √ | √ |
| 23 | FL.NET SYSTEM | S-7890-30 | 07-03 | √ | √ |
| 24 | D.NET SYSTEM | S-7890-31 | 07-04 | √ | √ |
| 25 | LADDER CHART MONITOR SYSTEM | S-7890-34 | 07-04 | √ | √ |
| 26 | HI-FLOW MONITOR SYSTEM | S-7890-35 | 07-01 | √ | √ |
| 27 | IR.LINK SYSTEM | S-7890-36 | 07-02 | √ | √ |
| 28 | Crossing C compiler (manufactured by Mentor graphics company) | MCP68K | 5.3 | √ (*2) | ns (*1) |

√: Supported ns: Not supported

(*1) Crossing C compiler (No.28) is not supported by Windows® XP. Use it on Windows® 2000.

(*2) Crossing C compiler (No.28) must be a version supported by Windows® 2000 (later than version 5.3) as a premise.

<Definitions of Terms>

N coil: A ladder program converted into a form that can be run on the PCs by pasting a symbol on the sheet displayed on a PC.

Process: A HI-FLOW program converted into a form that can be run on the PCs by pasting a symbol on the sheet displayed on a PC.

Compile: To convert an application program such as a ladder chart and HI-FLOW into a form (N coil, process, etc.) that can be run on the PCs.

Build: To compile only a corrected application program.

Rebuild: To compile every existing application program.

Sheet: Paper to prepare an application program of ladder chart and HI-FLOW, etc. This paper is controlled on a PC.

PCs: An abbreviation of Programmable Controllers.
This is a general term for PLC such as the S10 α and S10mini series.

PLC: An abbreviation of Programmable Logic Controller.
This is an industrial electronic device to exert sequence control, having an incorporated program.
The S10 α and S10mini series come under this PLC.

<Note for storage capacity calculations>

- Memory capacities and requirements, file sizes and storage requirements, etc. must be calculated according to the formula 2^n . The following examples show the results of such calculations by 2^n (to the right of the equals signs).

1 KB (kilobyte) = 1024 bytes

1 MB (megabyte) = 1,048,576 bytes

1 GB (gigabyte) = 1,073,741,824 bytes

- As for disk capacities, they must be calculated using the formula 10^n . Listed below are the results of calculating the above example capacities using 10^n in place of 2^n .

1 KB (kilobyte) = 1000 bytes

1 MB (megabyte) = 1000^2 bytes

1 GB (gigabyte) = 1000^3 bytes

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1 BEFORE USE

1 BEFORE USE

This manual is intended for personal computer programmers using the Windows®.

1.1 System Overview

The high-speed remote I/O system for Windows® (hereinafter simply referred to as the high-speed remote I/O system) is used to accomplish any of the following tasks through operations similar to those used by Windows® application users:

- Registering the mounting slot in which a HITACHI-S10α series high-speed remote I/O module is inserted
- Transmitting the system program
- Comparing the system program
- Registering on the user arithmetic function edition table

1.2 Hardware and Software Requirements

Using each system requires the following hardware and software.

<Personal Computers (hereafter abbreviated as PC)>

| Item \ OS | Windows® 95 (*1) | Windows® 2000 (*1) | Windows® XP (*1) |
|---|---|--------------------|-------------------------|
| | Windows® 98 (*1) | | (*2) |
| CPU | Pentium 133 MHz or more | | Pentium 300 MHz or more |
| Memory (RAM) | 32 MB or more | 64 MB or more | 128 MB or more |
| Free hard disk capacity (*3) | 20 MB or more/system (However, 10 MB or more/system for OS loading and option module support software) | | |
| Floppy disk drive | 1 unit or more (required to install software by FD) | | |
| CD-ROM drive | 1 unit or more (required to install software by CD-ROM) | | |
| Ethernet (10BASE-T) | 1 port or more (required to connect a PC with the ET.NET module) | | |
| Serial (D-sub 9-pin) | 1 port or more (required to connect the PCs with a PC by RS-232C or set an IP address for the ET.NET module) | | |
| PC card (conforming to the PC Card Standard (JEITA V4.2) TYPE II or TYPE III) | 1 slot or more (required to connect a PC with the parallel interface module (LWZ400). At this time, the following GP-IB card is also required.) GP-IB card: PCMCIA-GPIB (Model: 777438-02) (manufactured by National Instruments Corporation) | | |
| Display | Resolution of 800 × 600 pixels or more | | |
| Microsoft® Internet Explorer | Version 4.01 or later | | |

(*1) For the OS service pack, refer to the attached reference materials for software.

(*2) No.10 and No.28 in <Table of Systems Supported by Windows® 2000 and Windows® XP> in “PREFACE” are excepted.

(*3) This is a capacity required to install each system. A free capacity to save user programs is also required.

<Hardware other than PC>

- CPU for HITACHI-S10 α series (2 α , 2 α E, 2 α H, 2 α Hf)
- Power supply for HITACH-S10 α series
- Backboard for HITACHI-S10 α series
- HIGH SPEED REMOTE I/O module (LWE100) for HITACHI-S10 α series
- Connection cable between the personal computer and PCs
- Remote I/O stations, other power supplies and backboards, cards, and wiring as requires

NOTICE

Users of this product require knowledge of the Windows® environment and user interface. The high-speed remote I/O system conforms to the Windows® standard. This manual is intended for users who have mastered the basic usage of Windows®.

NOTE FOR PERSONAL COMPUTER SETTING

When you use a personal computer with the suspend function, disable the function. The personal computer may malfunction if the suspend function remains enabled during execution of the high-speed remote I/O system.

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2 INSTALLATION

2 INSTALLATION

2.1 Installing the System (*)

First, check if your CD is correct.

To install each system, double-click the Setup.exe file saved in the DISK1 folder of the system CD. After installing it, an installed program window is not displayed.

To install each system, install Microsoft® Internet Explorer 4.01 or later. If it is not installed, install each system after installing it.

NOTE

- To operate each system, install Microsoft® Internet Explorer 4.01 or later. If it is not installed, each system does not operate normally.
- Before installing each system, be sure to terminate such a program residing in the memory as virus monitoring software. If each system is installed without terminating the program, an error may occur. In this case, uninstall the system by referring to “2.2 Uninstalling the System” and terminate all Windows® programs. Then, install each system once again.
- To install and uninstall each system by using Windows® 2000, set “Administrator” or “Member of Administrators” as the user account to be logged on.
- To install and uninstall each system by using Windows® XP, set “Computer administrator” as the user account to be logged on. If “Account with limitations” is set, each system does not operate normally.

(*) No.10 and No.28 in <Table of Systems Supported by Windows® 2000 and Windows® XP> in “PREFACE” are excepted.

2.2 Uninstalling the System (*)

To uninstall each system for version-up, observe the following procedure.

(1) Uninstalling from Windows® 95 or Windows® 98

Open [Settings] in the [Start] menu – [Control Panel]. Double-click [Add/Remove Programs], select “Each System” by the [Install/Uninstall] tab, and click the button. When the [Confirm File Deletion] window is displayed, click the button.

(2) Uninstalling from Windows® 2000

Open [Settings] in the [Start] menu – [Control Panel]. Double-click [Add/Remove Programs], click [Change or Remove Programs], select “Each System,” and click the button. When the [Confirm File Deletion] window is displayed, click the button.

(3) Uninstalling from Windows® XP

Open ([Settings] –) [Control Panel] in the [Start] menu. Double-click [Add or Remove Programs], click [Change or Remove Programs], select “Each System,” and click the button. When the [Confirm File Deletion] window is displayed, click the button.

When a shortcut of each system executable file has been created on the desktop, etc. delete this shortcut.

NOTE

- When the [Remove Shared File?] window is displayed while each system is uninstalled on Windows®, click not to delete the shared file.
- To install and uninstall each system by using Windows® 2000, set “Administrator” or “Member of Administrators” as the user account to be logged on.
- To install and uninstall each system by using Windows® XP, set “Computer administrator” as the user account to be logged on.
- If the [Add/Remove Programs] window is locked (inoperable) when each system is uninstalled by using Windows® 2000, log off from [Shut Down] in the [Start] menu of Windows®, and then log on again on the [Log On to Windows] window.

(*) No.10 and No.28 in <Table of Systems Supported by Windows® 2000 and Windows® XP> in “PREFACE” are excepted.

2 INSTALLATION

2.3 Starting Up the System (*)

- (1) The system to be installed by each system is automatically registered in the [Start] menu of Windows®. From this [Start] menu, select [Programs (All Programs)] – [Hitachi S10] – “Each System” to start the system.

If the logged-on user name in installing each system is different from the user name in starting each system, each system is not displayed in the [Start] menu. In this case, create a shortcut of the executable file (extension .exe) for each system shown below and then double-click this shortcut to start each system.

<Executable File Storage Directory Table>

| No. | System name | Type | Executable file storage directory (*1) | Executable file name |
|-----|------------------------------|-----------|--|----------------------|
| 1 | S10Tools SYSTEM | S-7890-01 | C:\Hitachi\S10 | S10Ladder.exe |
| | | | | S10Tool.exe |
| 2 | LADDER CHART SYSTEM | S-7890-02 | C:\Hitachi\S10\2ALDC | S10Ladder.exe |
| 3 | HI-FLOW SYSTEM | S-7890-03 | C:\Hitachi\S10\HF | S10Tool.exe |
| 4 | CPMS LOADING SYSTEM | S-7890-04 | C:\Hitachi\S10\CPMS | Cpms.exe |
| 5 | CPMSE LOADING SYSTEM | S-7890-05 | C:\Hitachi\S10\CPMSE | Cpmse.exe |
| 6 | CPMS DEBUGGER SYSTEM | S-7890-06 | C:\Hitachi\S10\DEBUG | Debugger.exe |
| 7 | CPMSE DEBUGGER SYSTEM | S-7890-07 | C:\Hitachi\S10\DEBUGE | DebuggerE.exe |
| 8 | GP-IB LOADING SYSTEM | S-7890-08 | C:\Hitachi\S10\GPIB | Gpib.exe |
| 9 | BACKUP RESTORE SYSTEM | S-7890-09 | C:\Hitachi\S10\BACKUP | SysAllSaveLoad.exe |
| 10 | NX/Tools-S10 SYSTEM | S-7890-13 | C:\Hitachi\S10\NX | NXTool.exe |
| 11 | 4α LADDER CHART SYSTEM | S-7890-17 | C:\Hitachi\S10\4ALDC | S10Ladder_4A.exe |
| 12 | 4αH LADDER CHART SYSTEM | S-7890-18 | C:\Hitachi\S10\4AHLDC | S10Ladder_4AH.exe |
| 13 | LADDER COMMENT CONVERTER SYS | S-7890-19 | C:\Hitachi\S10\CFCONV | Cfconv.exe |
| 14 | HIGH SPEED REMOTE I/O SYSTEM | S-7890-21 | C:\Hitachi\S10\HISRIO | HiSpeedRIO.exe |
| 15 | CPU LINK SYSTEM | S-7890-22 | C:\Hitachi\S10\CPULINK | CpuLink.exe |
| 16 | 4ch ANALOG PULSE COUNTER SYS | S-7890-23 | C:\Hitachi\S10\ANALOG | AnalogPuls.exe |
| 17 | EXTERNAL SERIAL LINK SYSTEM | S-7890-24 | C:\Hitachi\S10\EXLINK | ExLink.exe |
| 18 | S10ET LINK SYSTEM | S-7890-25 | C:\Hitachi\S10\ETLINK | EtherNet.exe |
| 19 | J.NET SYSTEM | S-7890-27 | C:\Hitachi\S10\JNET | JNet.exe |
| 20 | OD.RING/SD.LINK SYSTEM | S-7890-28 | C:\Hitachi\S10\ODRING-SDLINK | ODRing.exe |
| 21 | ET.NET SYSTEM | S-7890-29 | C:\Hitachi\S10\ETNET | Et_Net.exe |
| 22 | FL.NET SYSTEM | S-7890-30 | C:\Hitachi\S10\FLNET | FLnet.exe |
| 23 | D.NET SYSTEM | S-7890-31 | C:\Hitachi\S10\DNET | DNet.exe |
| 24 | LADDER CHART MONITOR SYSTEM | S-7890-34 | C:\Hitachi\S10\2ALDCM | S10LadderM.exe |
| 25 | HI-FLOW MONITOR SYSTEM | S-7890-35 | C:\Hitachi\S10\HFM | S10ToolM.exe |
| 26 | IR.LINK SYSTEM | S-7890-36 | C:\Hitachi\S10\IRLINK | IrLink.exe |

(*1) Directory name when “C” is the drive name of installing destination.

(*) No.10 and No.28 in <Table of Systems Supported by Windows® 2000 and Windows® XP> in “PREFACE” are excepted.

- (2) The [HIGH SPEED REMOTE I/O SYSTEM] window is displayed, showing that the high-speed remote I/O system has been started up. Click the button for the desired command.

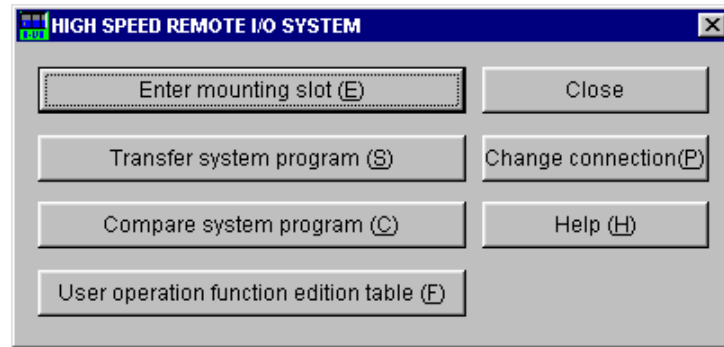


Figure 2-1 [HIGH SPEED REMOTE I/O SYSTEM] Window

2.4 Terminating the System

The high-speed remote I/O system is terminated by clicking the or button on the [HIGH SPEED REMOTE I/O SYSTEM] window (Figure 2-1).

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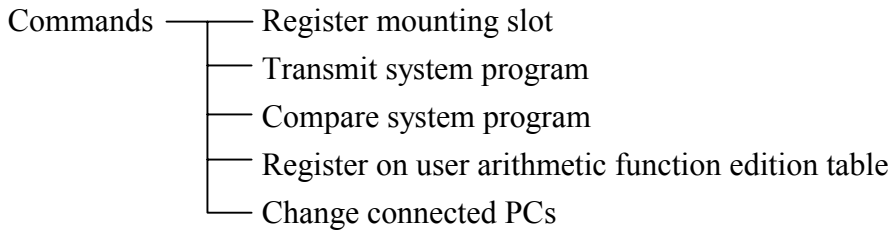
3 COMMANDS

3 COMMANDS

3.1 Command System

The high-speed remote I/O command system is shown below.

Each of these commands is described in Section 3.2 and later. For details on each command, refer to Help.

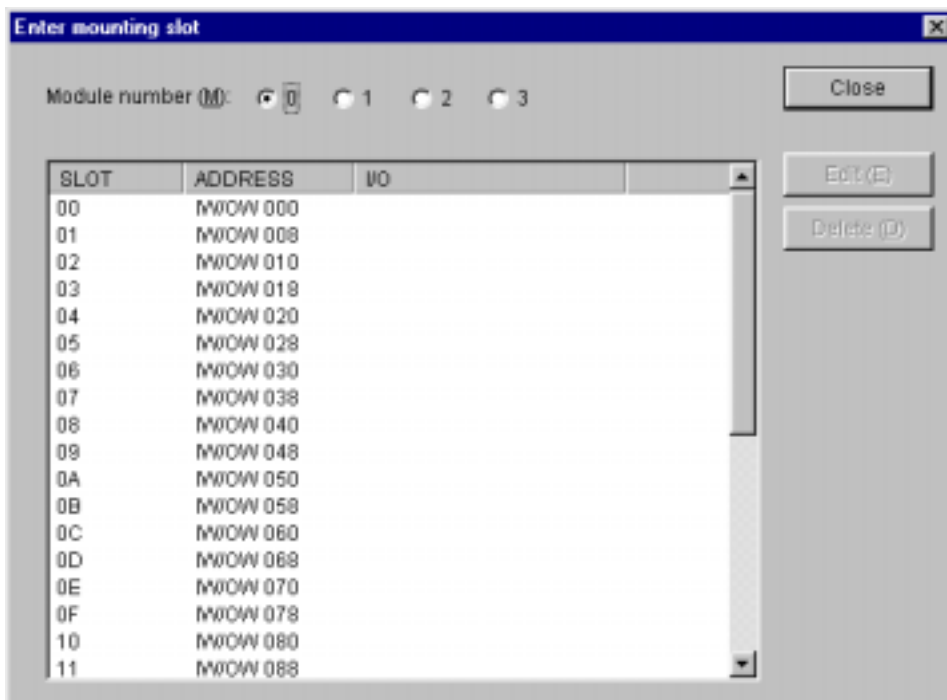


3.2 Registering mounting slot

Function: Assigns a registration number to a given I/O module and defines its module type.

Operation: See the operation procedure below.

- Click the button on the [HIGH SPEED REMOTE I/O SYSTEM] window.
- The [Enter mounting slot] window is displayed. Click the “Module number” and “SLOT” to be assigned, and then click the button.



- (3) The [Set] window is displayed. Set up the “I/O module.”

The screenshot shows a dialog box titled "Set" with a close button (X) in the top right corner. It contains the following elements:

- A text field labeled "Transfer slot number" with the value "00" entered.
- Two buttons: "OK" and "Cancel".
- A section labeled "I/O module (M):" with seven radio button options:
 - Digital input
 - Digital output
 - Analog input (2 channels)
 - Analog input (4 channels)
 - Analog output
 - Digital input (Int)
- A table with three columns: "Point (P)", "TNO.", and "FACT". The rows are labeled with points 8, 9, A, B, C, D, E, and F. Each cell in the "TNO." and "FACT" columns contains the number "0".

| Point (P) | TNO. | FACT |
|-----------|------|------|
| 8 | 0 | 0 |
| 9 | 0 | 0 |
| A | 0 | 0 |
| B | 0 | 0 |
| C | 0 | 0 |
| D | 0 | 0 |
| E | 0 | 0 |
| F | 0 | 0 |

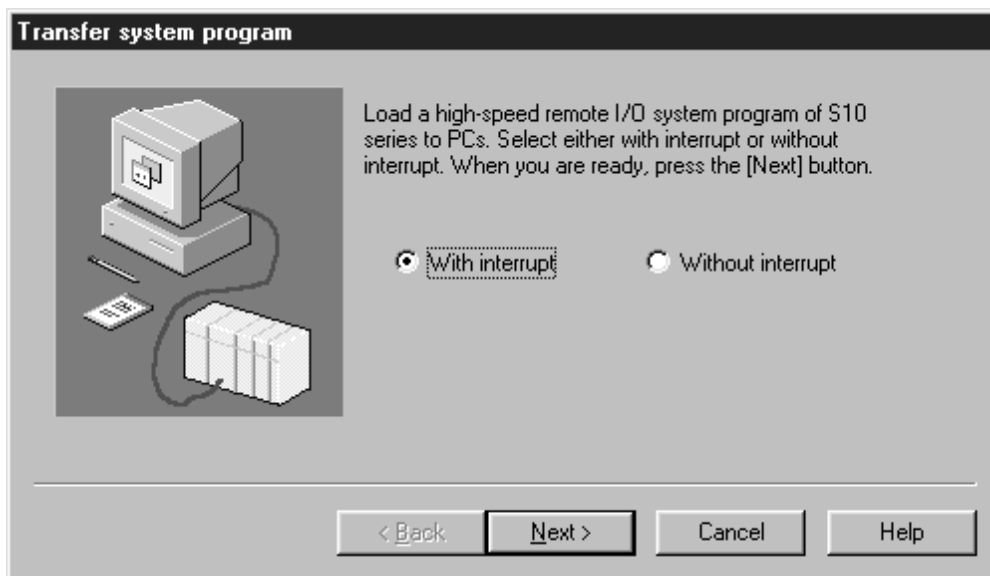
- (4) Digital input (Int) becomes usable after the high-speed remote I/O system program has been transmitted. See, “3.3 Transmitting System Program.”
- (5) After setting up is completed, click the **OK** button. If you want to cancel the setup, click the **Cancel** button.

3.3 Transmitting System Program

Function: Transmits the high-speed remote I/O system program to the PCs.

Operation: See the operation procedure below.

- (1) Click the **Transfer system program** button on the [HIGH SPEED REMOTE I/O SYSTEM] window.
- (2) The [Transfer system program] window is displayed.



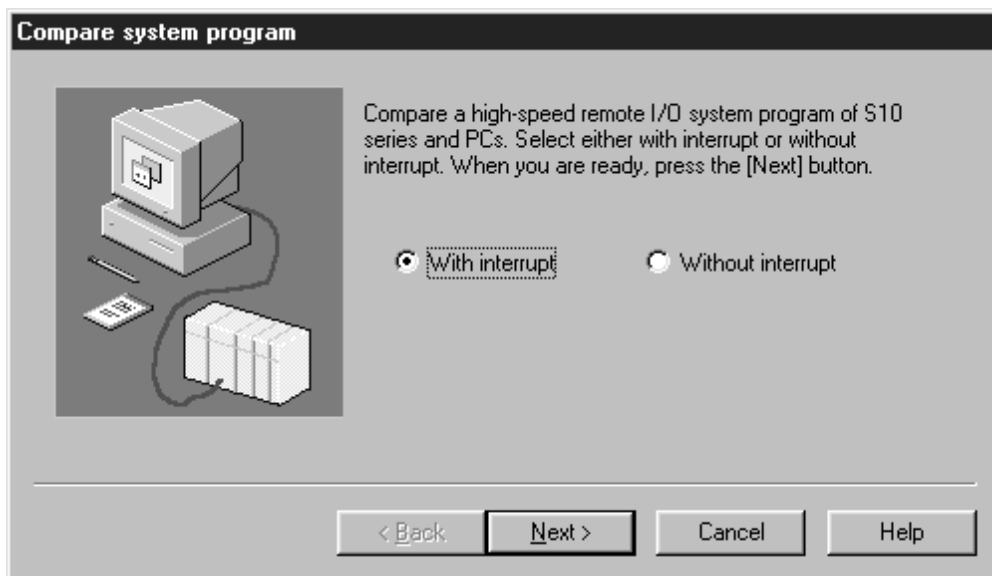
- (3) Select between the presence or absence of an interrupt mechanism, and click the **Next** button. System program transmission will then be started. If you do not want to transmit the system program, click the **Cancel** button.

3.4 Comparing System Program

Function: Compares the high-speed remote I/O system program and the contents of the PCs.

Operation: See the operation procedure below.

- (1) Click the **Compare system program** button on the [HIGH SPEED REMOTE I/O SYSTEM] window.
- (2) The [Compare system program] window is displayed.



- (3) Select between the presence or absence of an interrupt mechanism, and click the **Next** button. Comparison is then started. If you do not want to compare them, click the **Cancel** button.

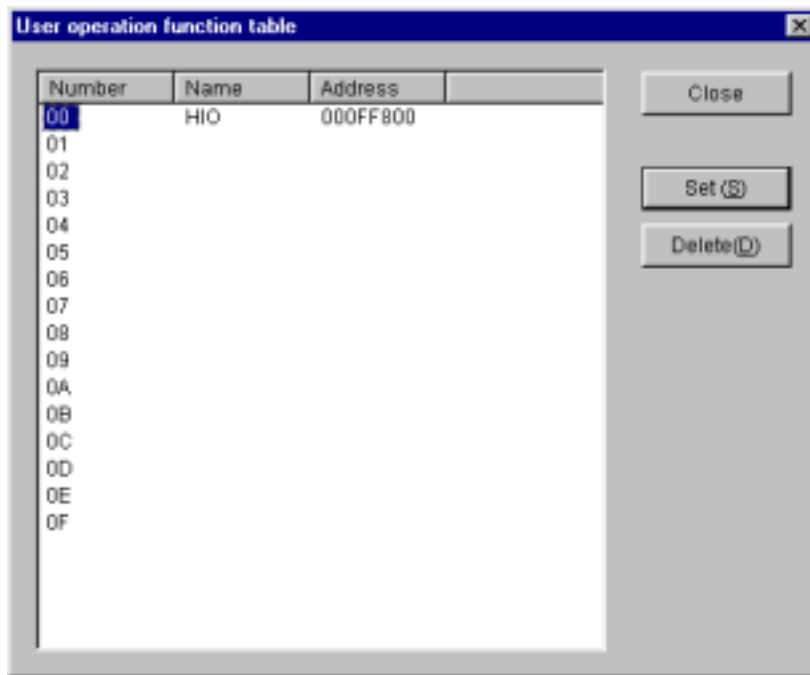
3 COMMANDS

3.5 User Operation Function Edition Table

Function: Registers user operation functions.

Operation: See the operation procedure below.

- (1) Click the button on the [HIGH SPEED REMOTE I/O SYSTEM] window.
- (2) The [User operation function table] window is displayed. Click the “Number” to be assigned to the function, and click the button.



- (3) The [Set] window is displayed. Enter the “Name.”



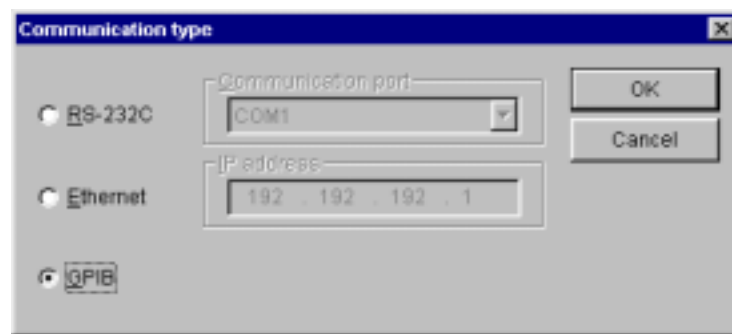
- (4) After setting up is completed, click the button. If you want to cancel the setup, click the button.

3.6 Changing Connected PCs

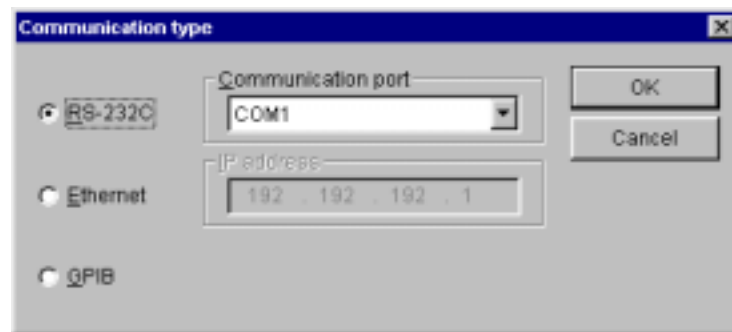
Function: Sets a specified communication type for the PCs and personal computer.

Operation: See the operation procedure below.

- (1) Click the **Change Connection** button on the [HIGH SPEED REMOTE I/O SYSTEM] window.
- (2) The [Communication type] window is displayed.



- (3) If the desired communication type is RS-232C, click the “RS-232C” radio button and select a “Communication port.”

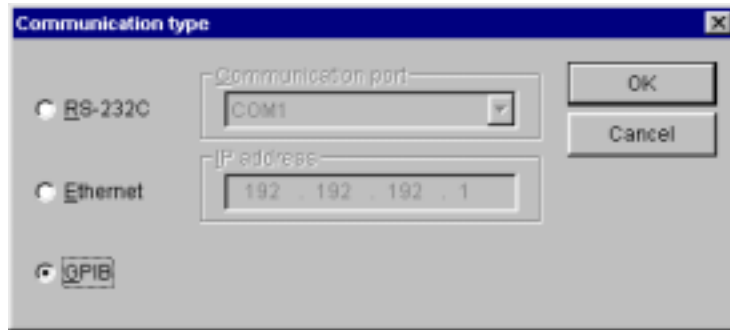


- (4) If it is Ethernet, click the “Ethernet” radio button and enter the “IP address” of the connection destination.



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- (5) If it is GP-IB, click the “GPIB” radio button.



- (6) When communication type selection is completed, click the **OK** button to set the selection. If you want to cancel the selection, click the **Cancel** button.